Week 2 (Supervisor meeting)

Meeting Date: 27/1

Meeting mins: 90mins

Meeting members: Jacko, Xu Cheng, Jeason, MingJi, Xueting, Hari

Meeting Content:

1. For the robot behaviour, each team needs 4 players in three classes. The interesting aspect of player behaviour could mean a shift in player roles as players and ball positions change.
2. The sensors for detecting the position of the ball are mainly cameras.
3. Focus on setups and functions.
4. The act of judging should be considered in relation to the role of the player, the position of the ball and the boundaries of the field.
5. Expect to devote more time costs.